

Sandstone Compaction Modelling and Reservoir Simulation

by
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Outline

- State of the art
- Model for sandstone compaction
- Adapt to simulation
- Improved coupled simulation
(rock mechanics ↔ flow simulation)

Compaction Modelling

- **Reservoir Simulator:** Compaction is a function of fluid pressure, $C_r = C_r(p_f)$
- **Reality:** Compaction is a function of effective stress
→ the difference between (confining) total stress and fluid pressure
- Measure for compaction in a simulator grid cell,
Pore Volume Multiplier,

$$PV_{mult} = \frac{\text{current cell pore volume}}{\text{initial cell pore volume}}$$

Computing PV_{mult}

- From reservoir simulator:
 $PV_{mult}(p_f)$ from $C_r(p_f)$ (table look-up)
- From rock mechanics simulator
 $PV_{mult}(\text{strain}) = \exp(-\Delta \text{ vol. strain})$

Fluid Pressure and Stress

For practical purposes,

$$\sigma' = \sigma - p_f$$

where

σ' and σ are effective and total stress

p_f is fluid pressure

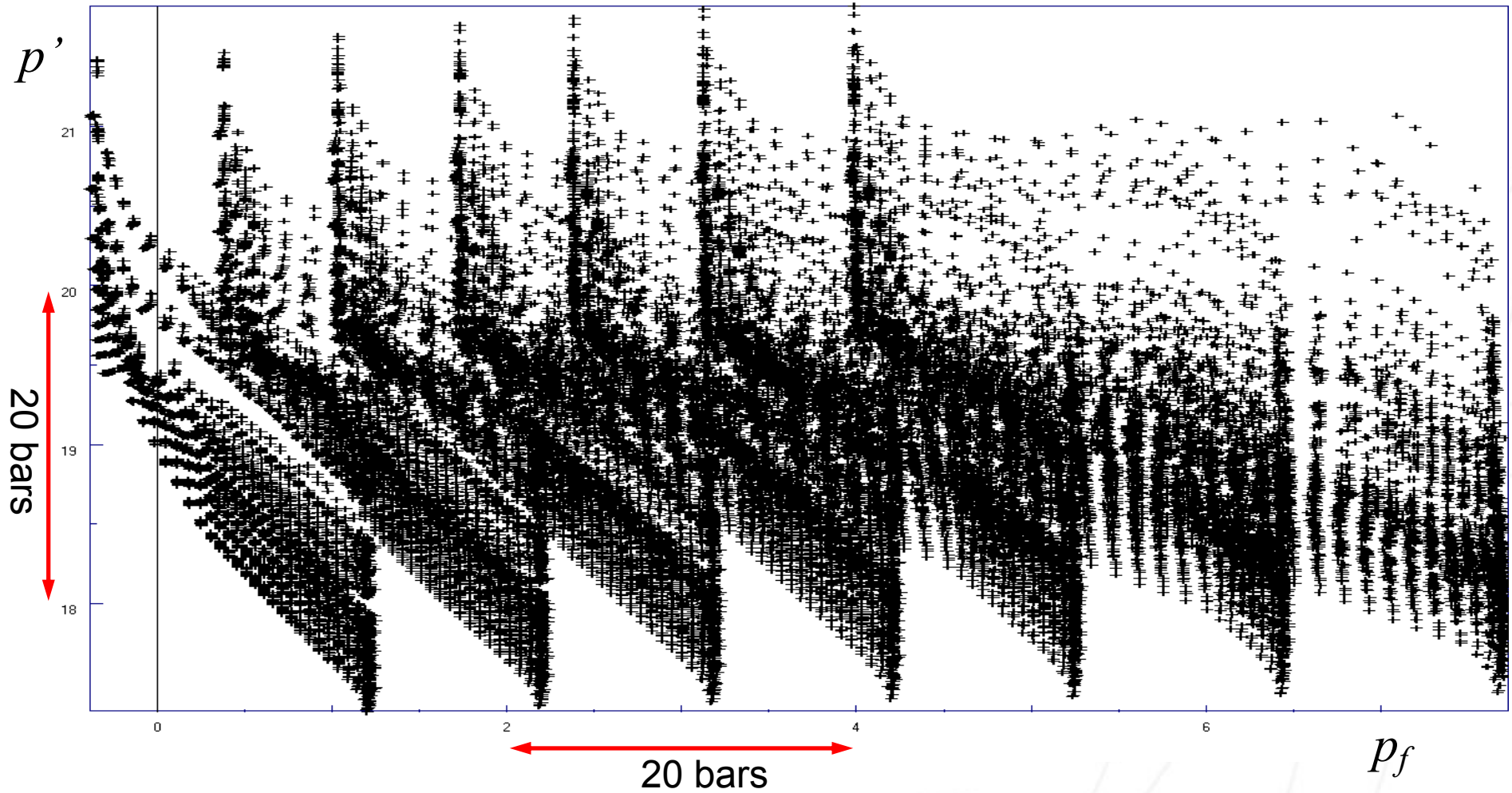
I.e.: Assuming compaction is a function of fluid pressure

is equivalent to assuming total stress is constant,

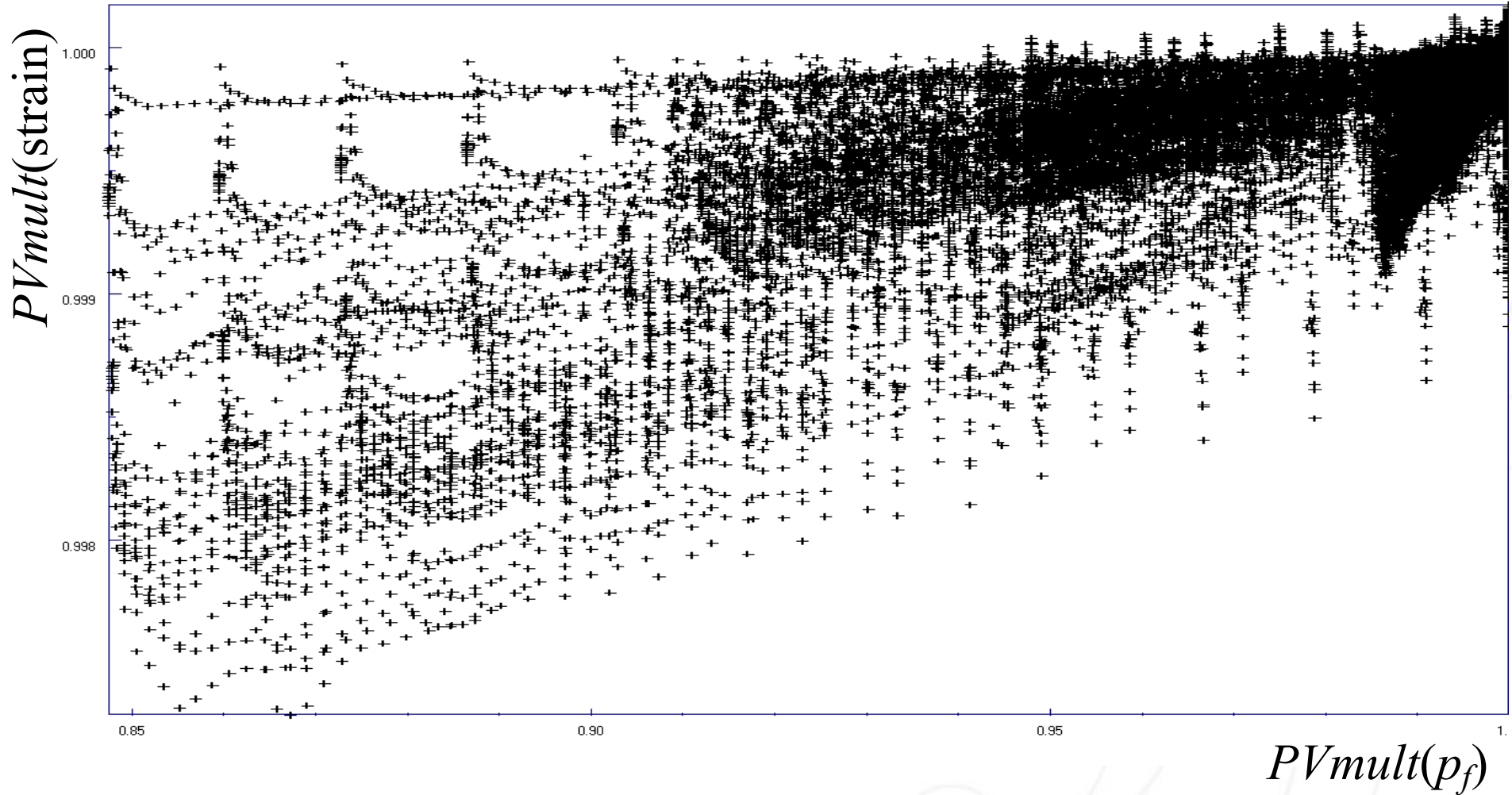
or

mean effective stress vs. fluid pressure is a straight line

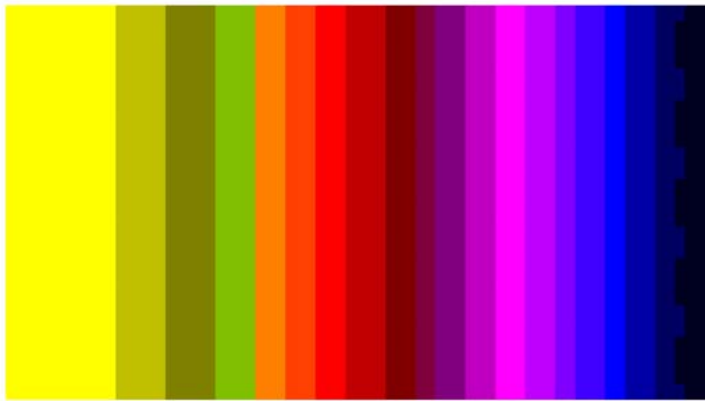
Correlation: Mean Eff. Stress vs. Fluid Pressure



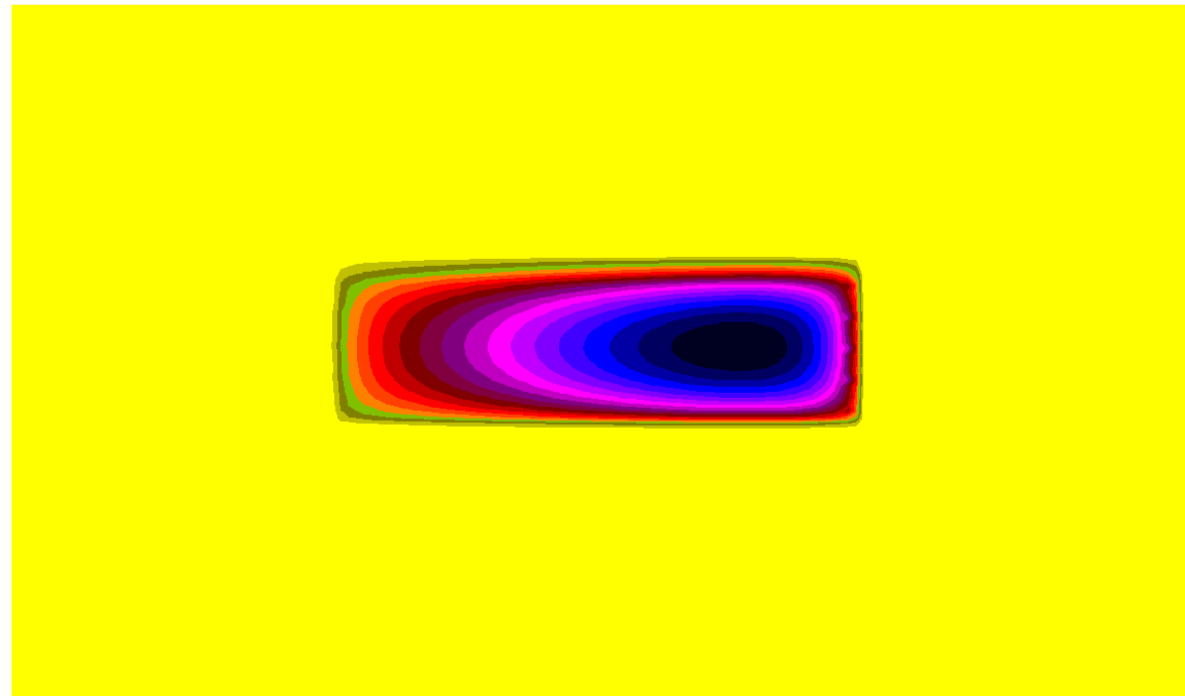
Correlation PV_{mult} : “Correct” vs. from p_f



The main reason for the discrepancy is that the reservoir simulator knows nothing about actual soil displacement in the reservoir. (Boundary effects – “arching”)



$PVmult(p_f)$
(Reservoir only)



$PVmult(\text{strain})$ (Reservoir and sideburdens)

There is a growing awareness that

- Dynamic reservoir stress state often has significant influence on petrophysics and fluid production
- These processes can only be understood by performing coupled simulations
(Rock mechanics simulator – Reservoir simulator)

In this study:

Finite Difference Reservoir simulator:
ECLIPSE from Schlumberger

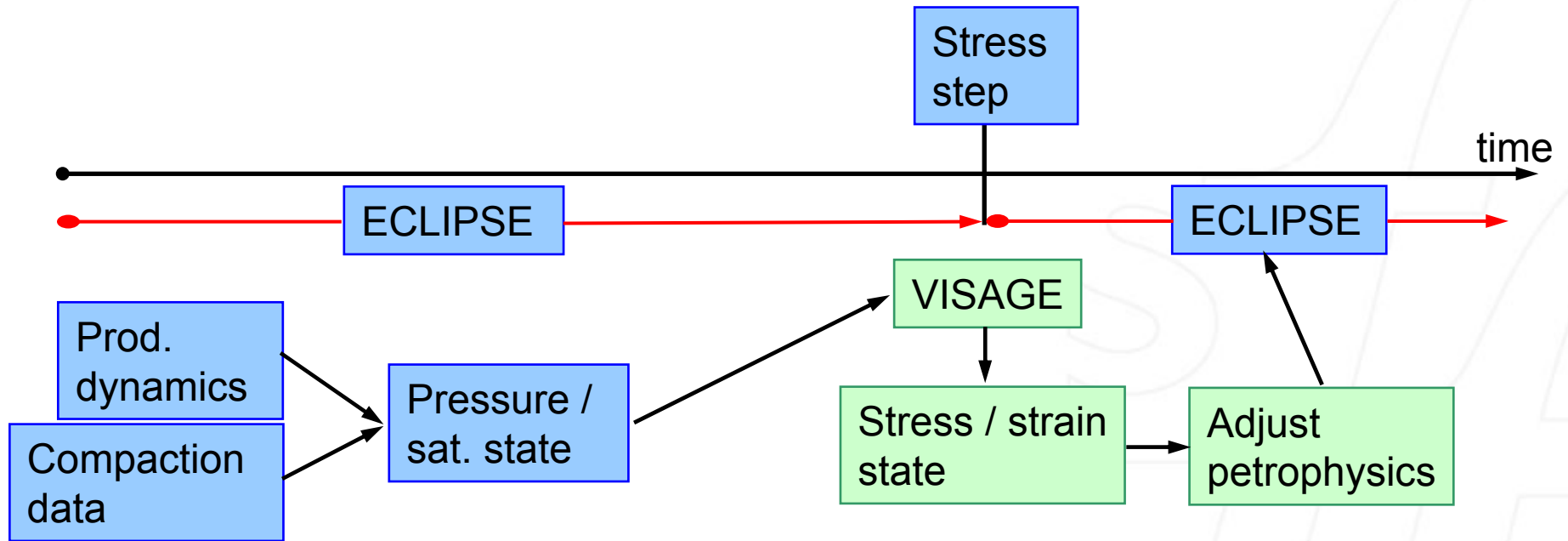
Finite Element Rock Mech. simulator:
VISAGE from V.I.P.S Ltd.



Coupling Modes

- Fully coupled
 - Full system of fluid flow and rock mechanics equations solved simultaneously at each time step
 - 👍 Most accurate solution
 - 👎 Takes long to run
 - 👎 No fully coupled simulator includes all options that exist in commercial flow simulators or rock mechanics simulators

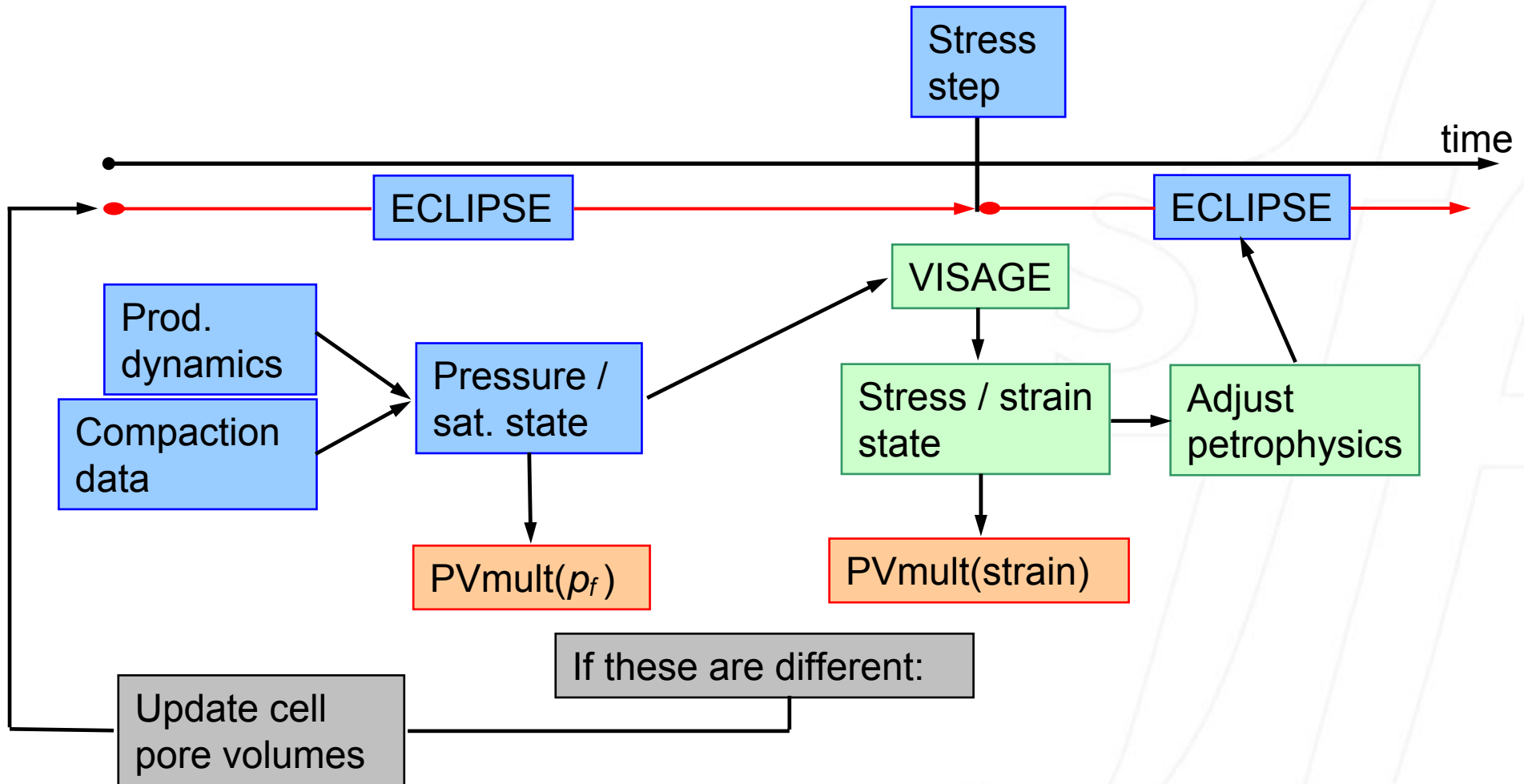
Coupling Modes: Explicit Coupling



Explicit Coupling

- 👍 Relatively fast
- 👍 Provides reasonably good reservoir stress state *distribution* (but not *level*)
- 👎 Questionable accuracy w.r.t. compaction modelling

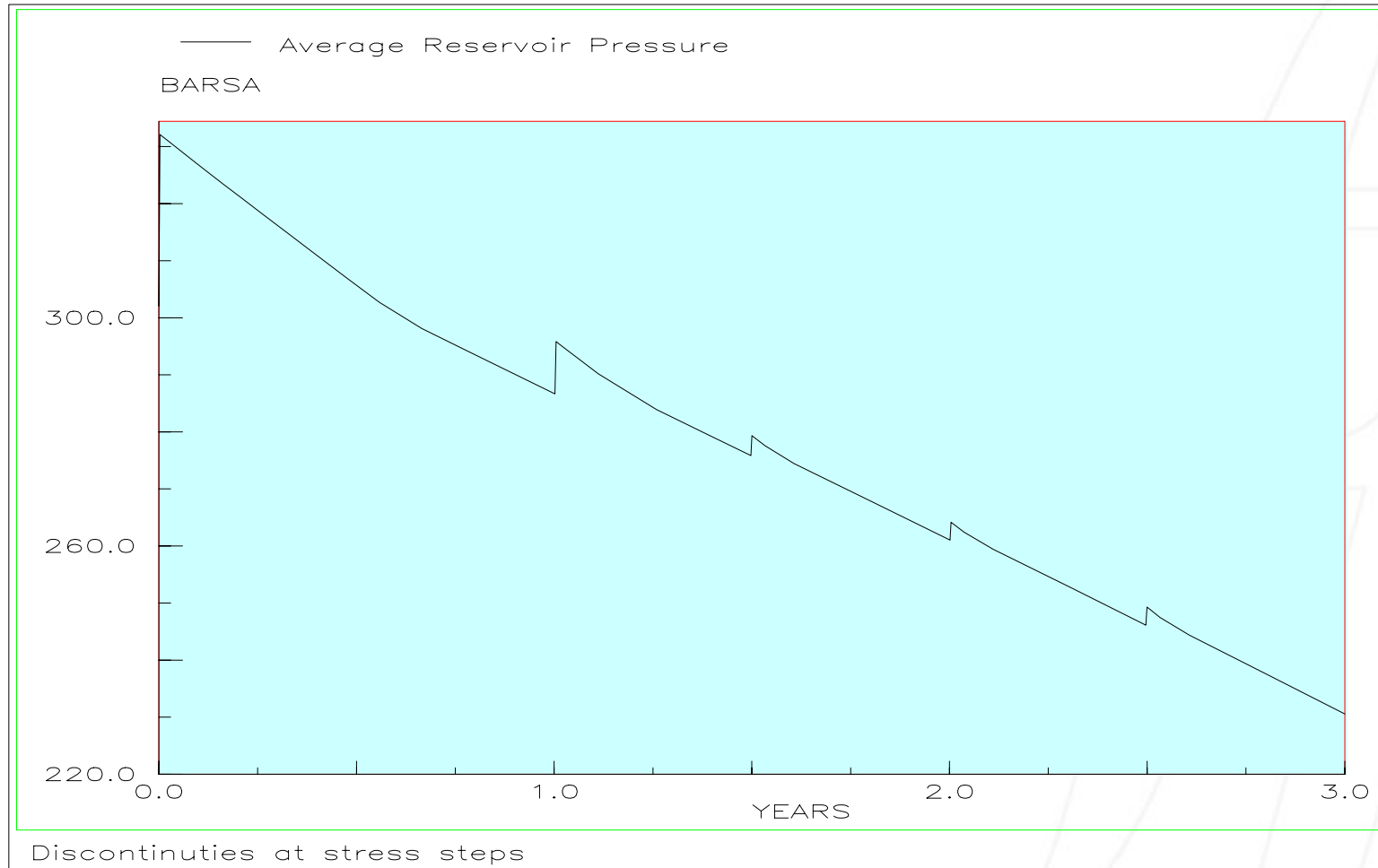
Coupling Modes: Iterative Coupling



Iterative Coupling

- 👍 Good reservoir stress state *distribution* and *level*,
 - Accurate compaction
- 👍 Can take long to run
- 👍 Updates performed only on stress steps
 - Pressure discontinuities

Pressure vs. Time in Iterative Coupled Run



Improved Coupling Scheme

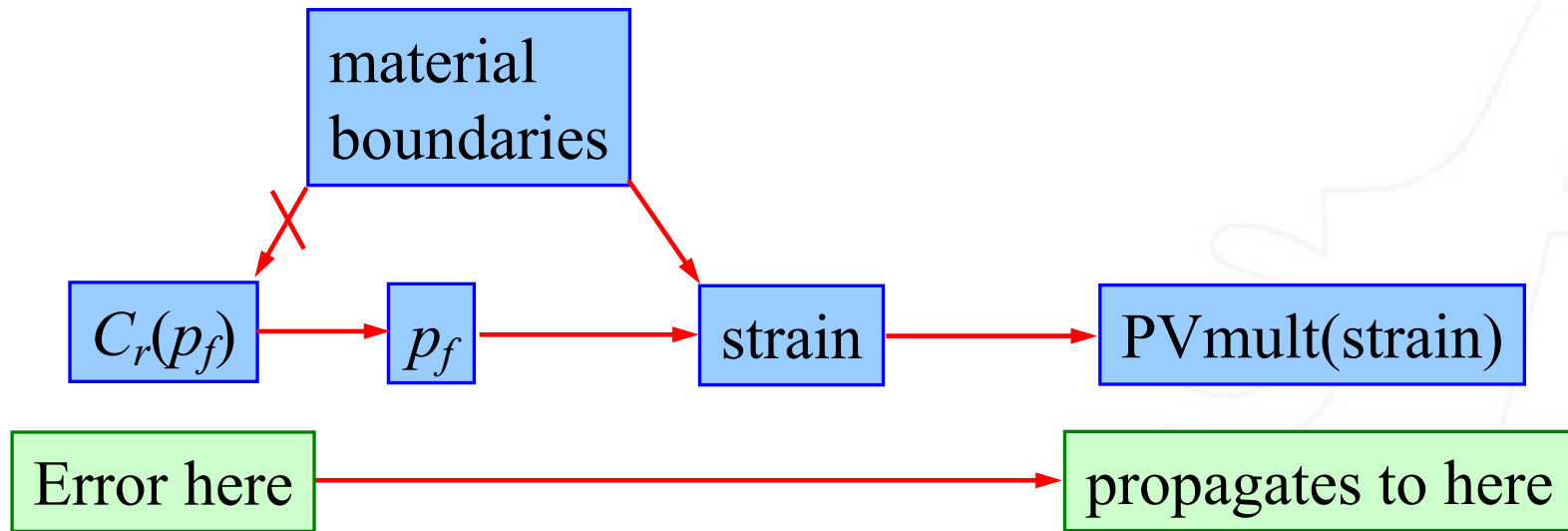
Evaluation chain:



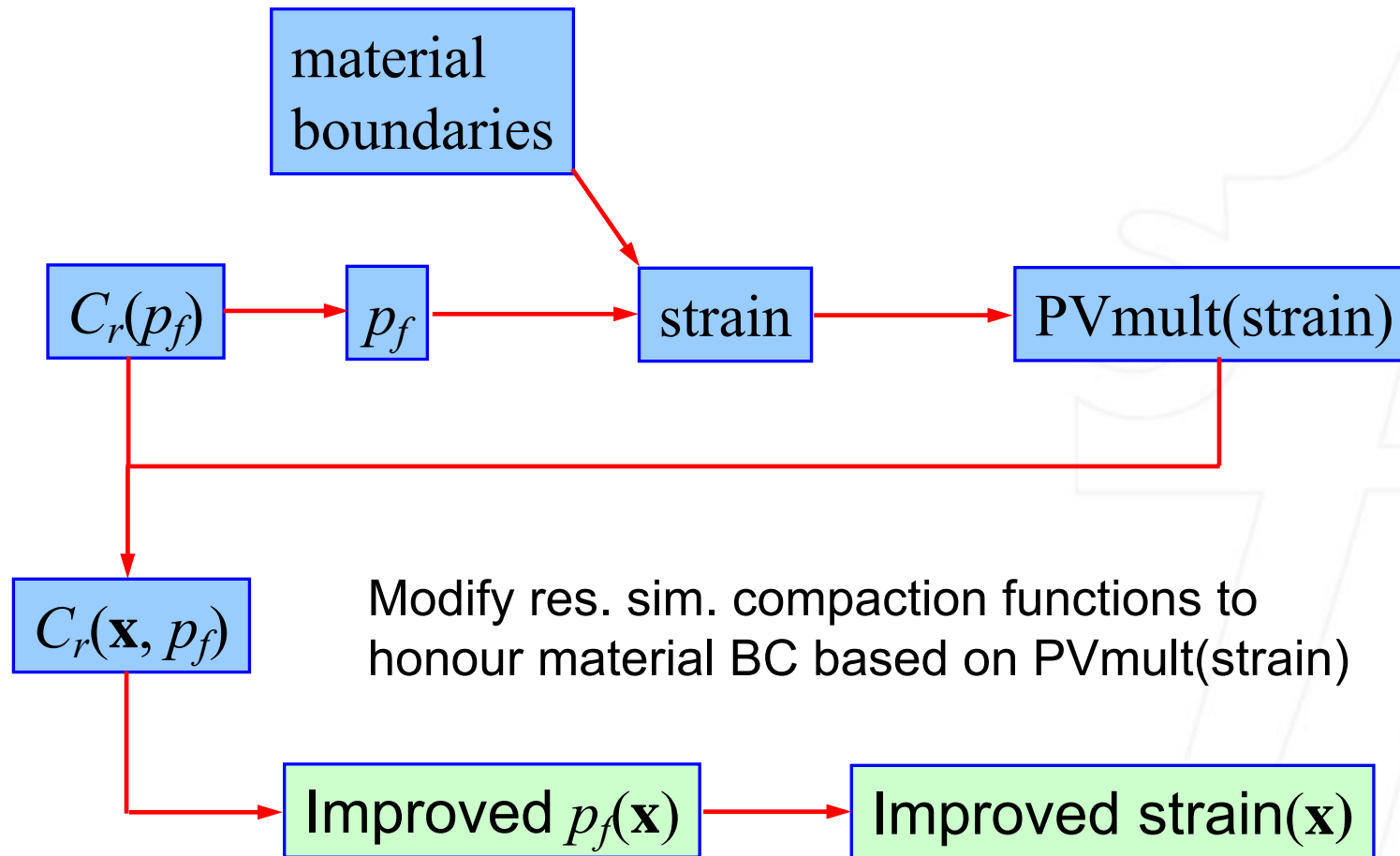
Reservoir simulator

Rock mech. simulator

Improved Coupling Scheme



Improved Coupling Scheme



Improved Coupling Scheme

- extend trends in $C_r(\mathbf{x}, p_f)$ in space and time to get a better predictor for stress simulations
- Modifications done on res. sim. data: Cont. pressure



Goal

- 😊 Faster than iterative coupling
- 😊 More accurate than explicit coupling

Consistent Compaction Model

- To proceed we need a compaction model which is “equivalent” in VISAGE and ECLIPSE
- Definition:
A compaction model is **consistent** if the flow simulator compaction function is derived from the rock mechanics poro-elasto-plastic model.

(Idealized) Grain Pack Model for Sand / Sandstone



Basis – Pure Geomechanical Compaction

- Typical measured bulk compressibilities for sands / sandstones are much smaller than grain compressibility
 - ✓ Grain (quartz): $K \sim 38 \text{ GPa}$
 - ✓ Sands: $K = 100 \text{ MPa} - 1 \text{ GPa}$
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- **Principle of Stable Settlement:**
When grain packing changes, it will always seek a more stable packing pattern.

Consequences

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 - the tightest possible packing at that state

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- As packing becomes tighter, further packing will be increasingly more difficult to achieve
 - each “packing level” is more stable than previous levels
 - Compressibility increases with load

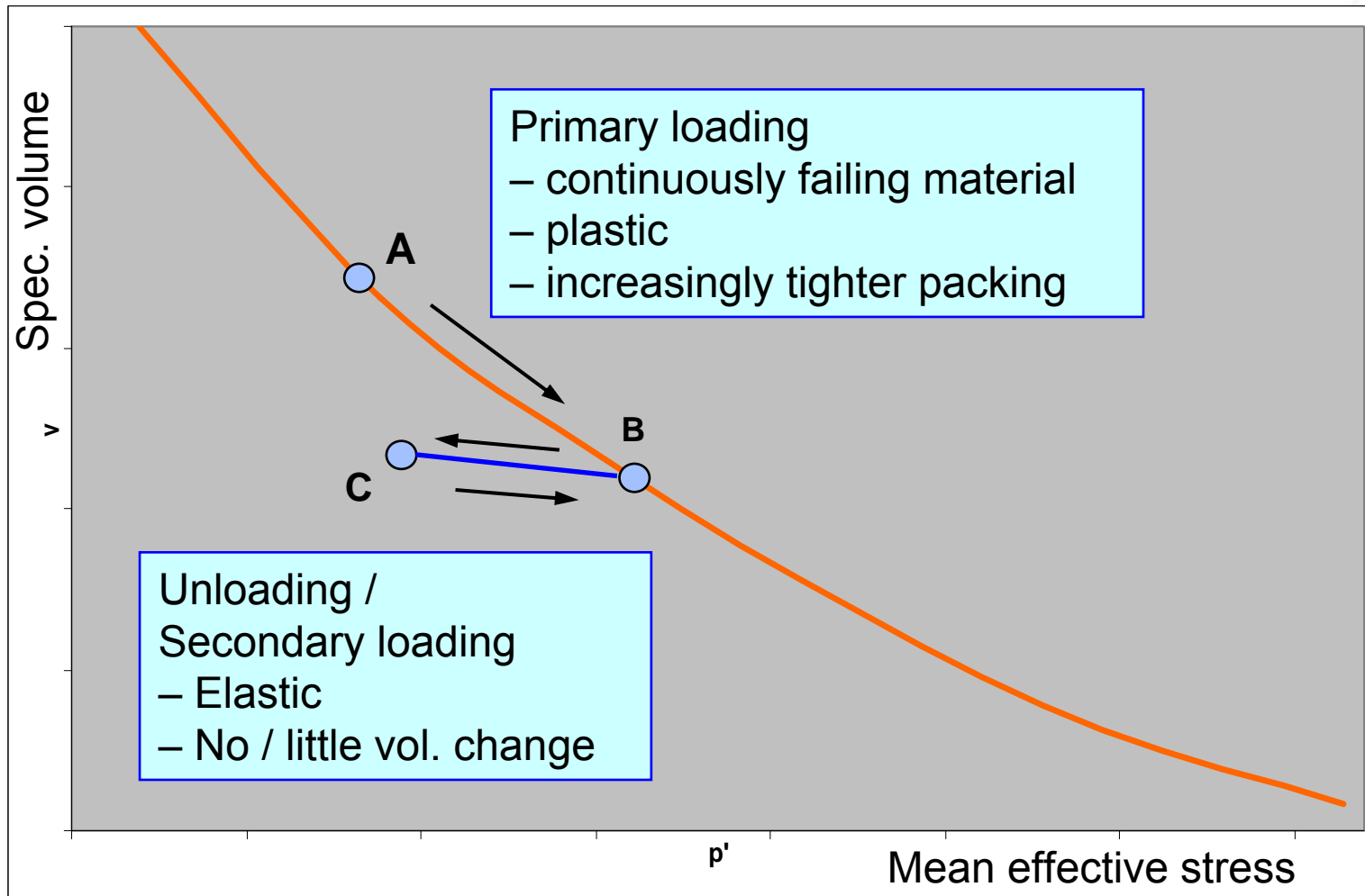
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- Relieving stress will *not* return the soil to a previous, *less stable* packing level

Implications

- At pore level, **continuous pore wall failure** is taking place during compaction
- At bulk level, compaction will be observed as **permanent deformation of pore space** (plasticity)
- The soil has *no memory* of its past stress history
 - each packing level can be seen as a “new” material with its own poro-elasto-plastic parameters

Characteristics of Grain Pack Model



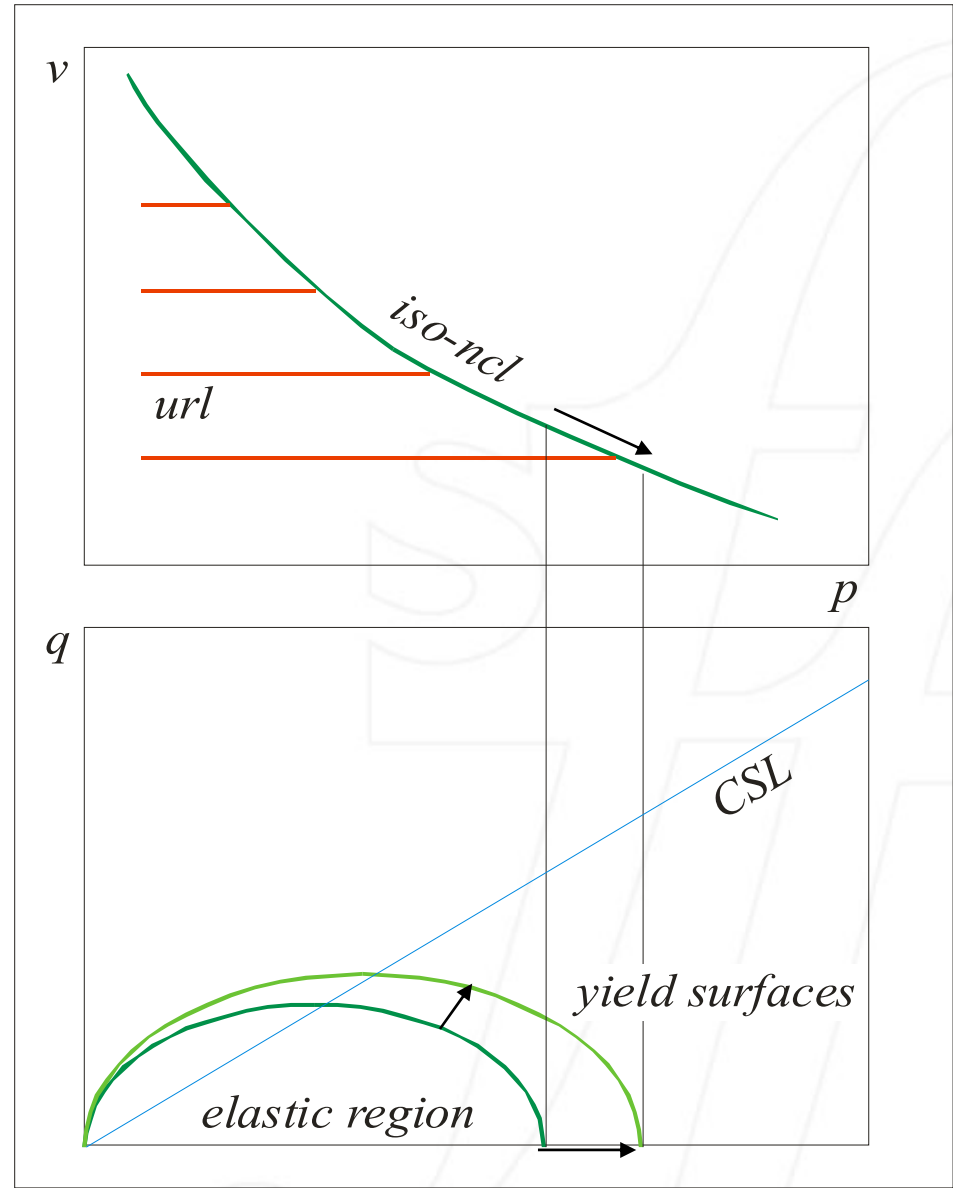
Hence, the grain pack model behaves according to **Critical State Theory**:

Change of v along iso-ncl (isotropic normal compression line) is determined by expansion of yield surface in the stress plane

Movement along url's (unloading-reloading lines) occurs in the elastic region in the stress plane

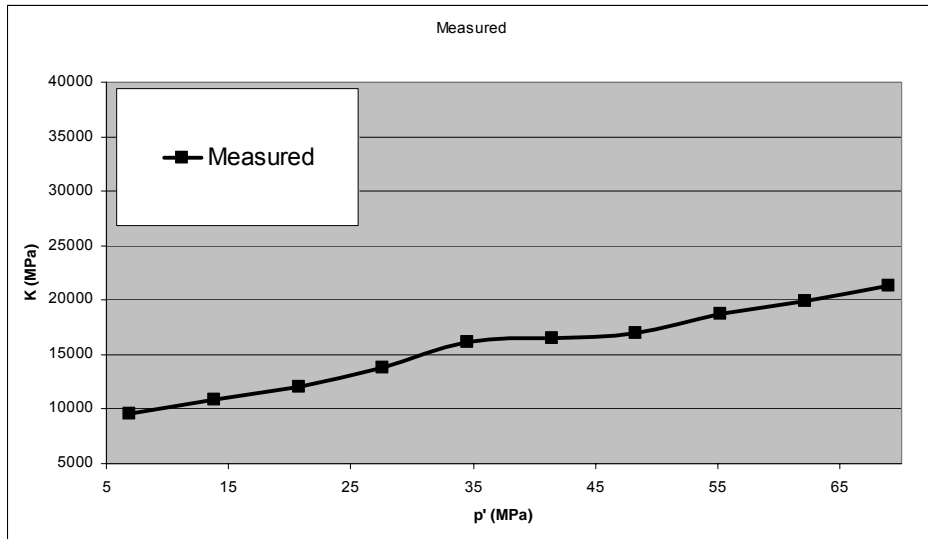
Yield surface expansion is determined by the **hardening rule**

$$\frac{\partial p}{\partial \varepsilon_p} = p \frac{v}{v_0} H$$



- **For sands / sandstones, Critical State Theory is *the* appropriate failure model to use.**
 - Not e.g. Mohr-Coulomb (the most popular choice).
 - Definitely not linear elastic
 - In practice we use the special case: Cam Clay Model

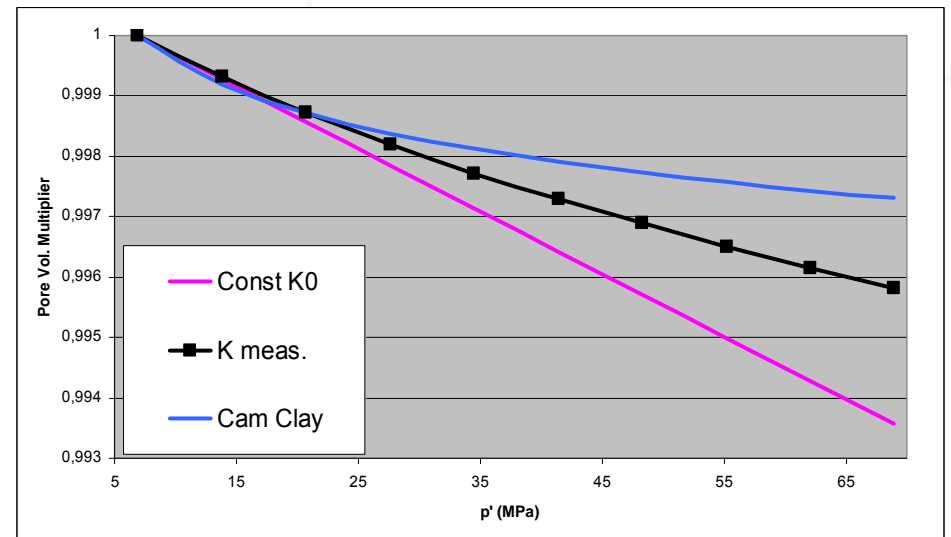
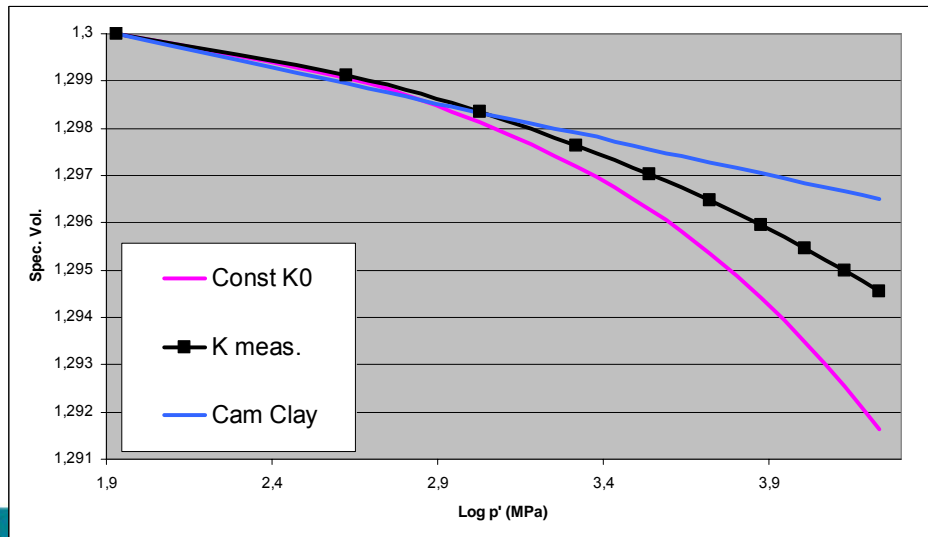
$K(p') \rightarrow C_r(p')$ (Med. Strength Sandstone)



$K(p')$

$v(p')$

PVmult(p')

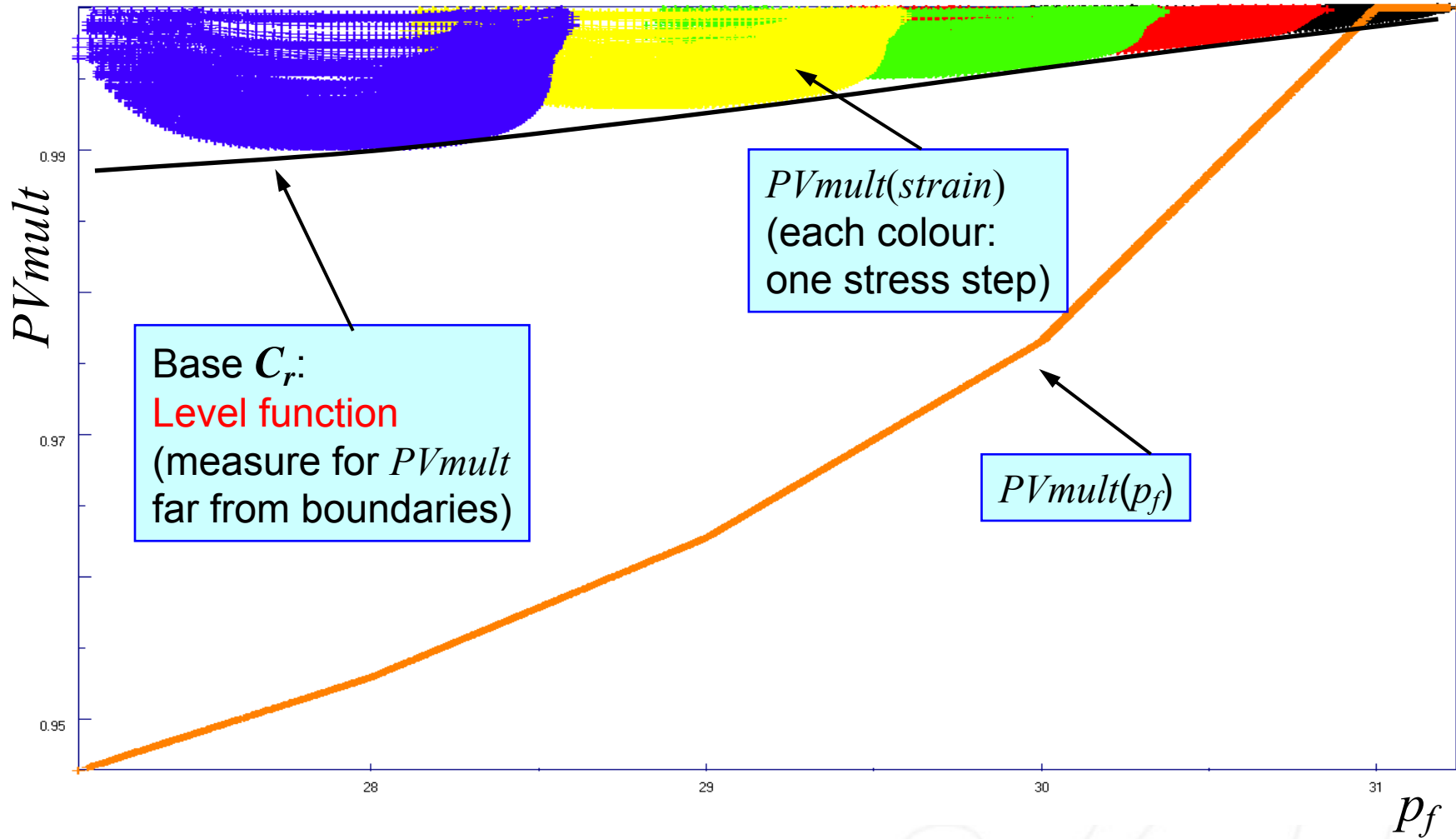


Calculating compaction distribution, Step by step

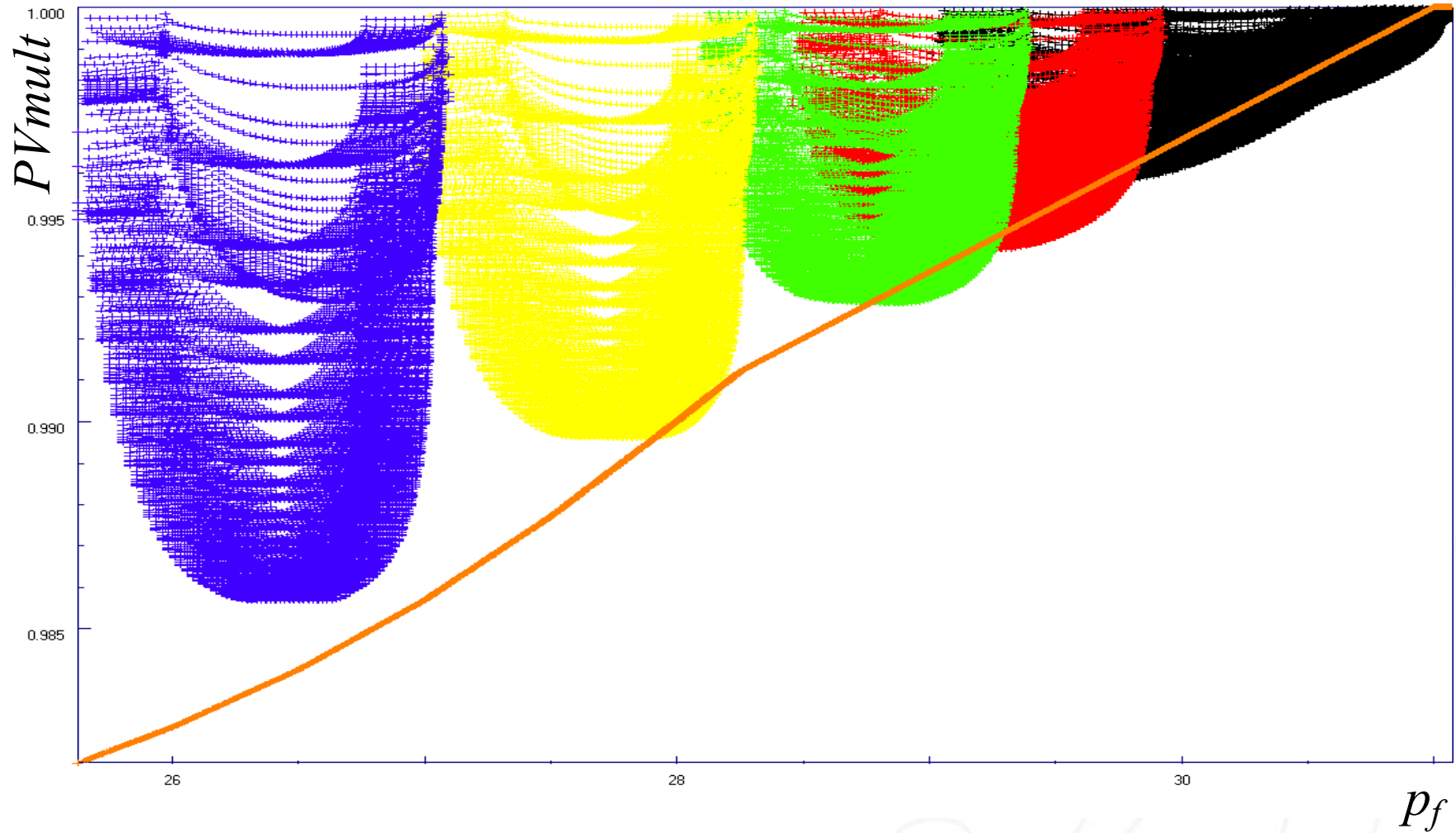
Rock Mech. Failure Model: Critical State (Cam Clay)
Flow Sim. Compaction function: Derived from Cam Clay

All calculations done on stress step 2; but complete simulation performed at each iteration, for illustrative purposes

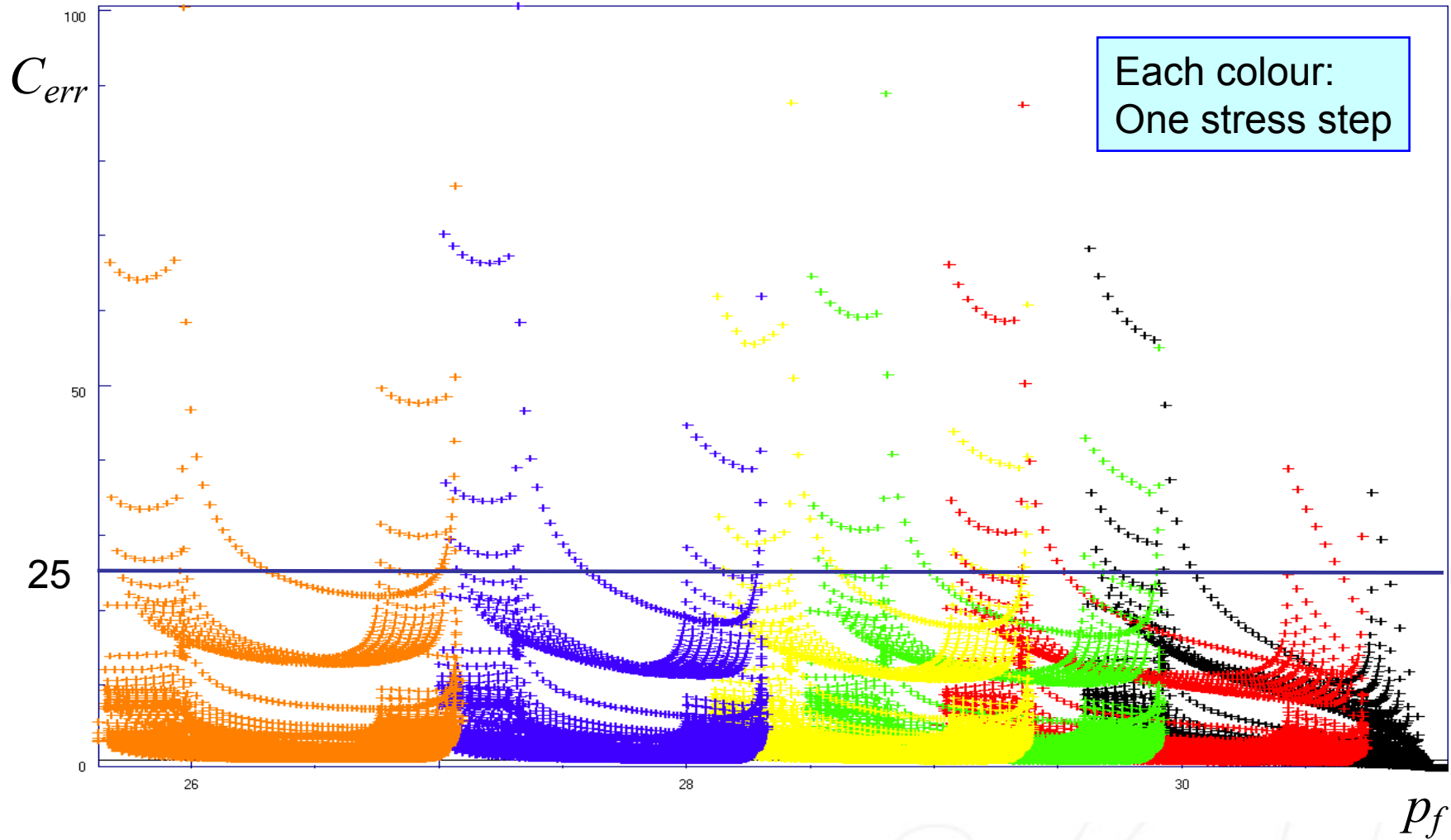
Iteration Step 1: Using $C_r(p_f)$ instead of $C_r(p')$



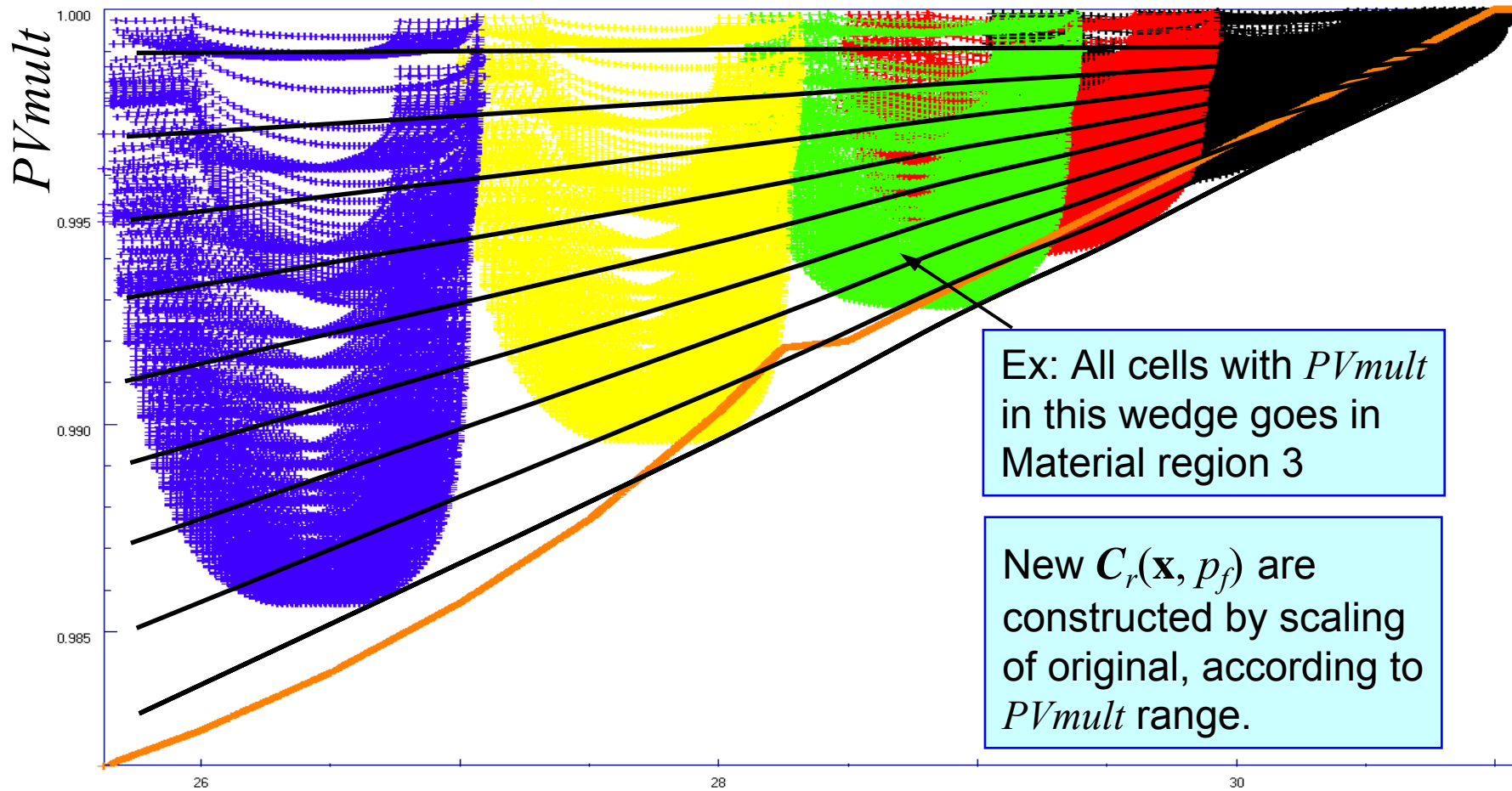
Iteration Step 2: Scale $C_r(p_f)$ to Level Function



Error in Compaction Computation



Iteration Step 3: Subdivide Reservoir into new Material Regions



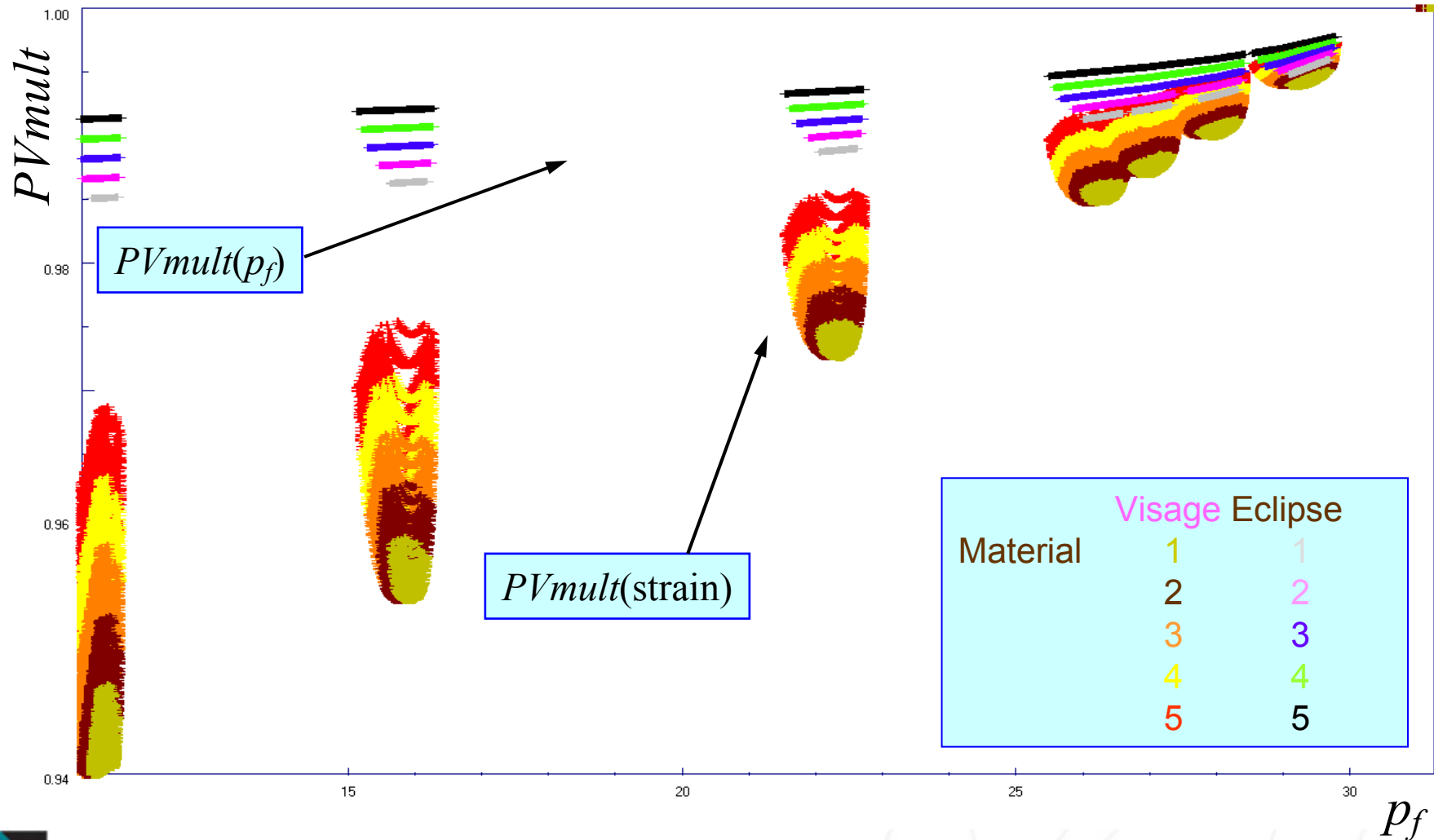
P_f

New Material Regions, XY View Middle Layer

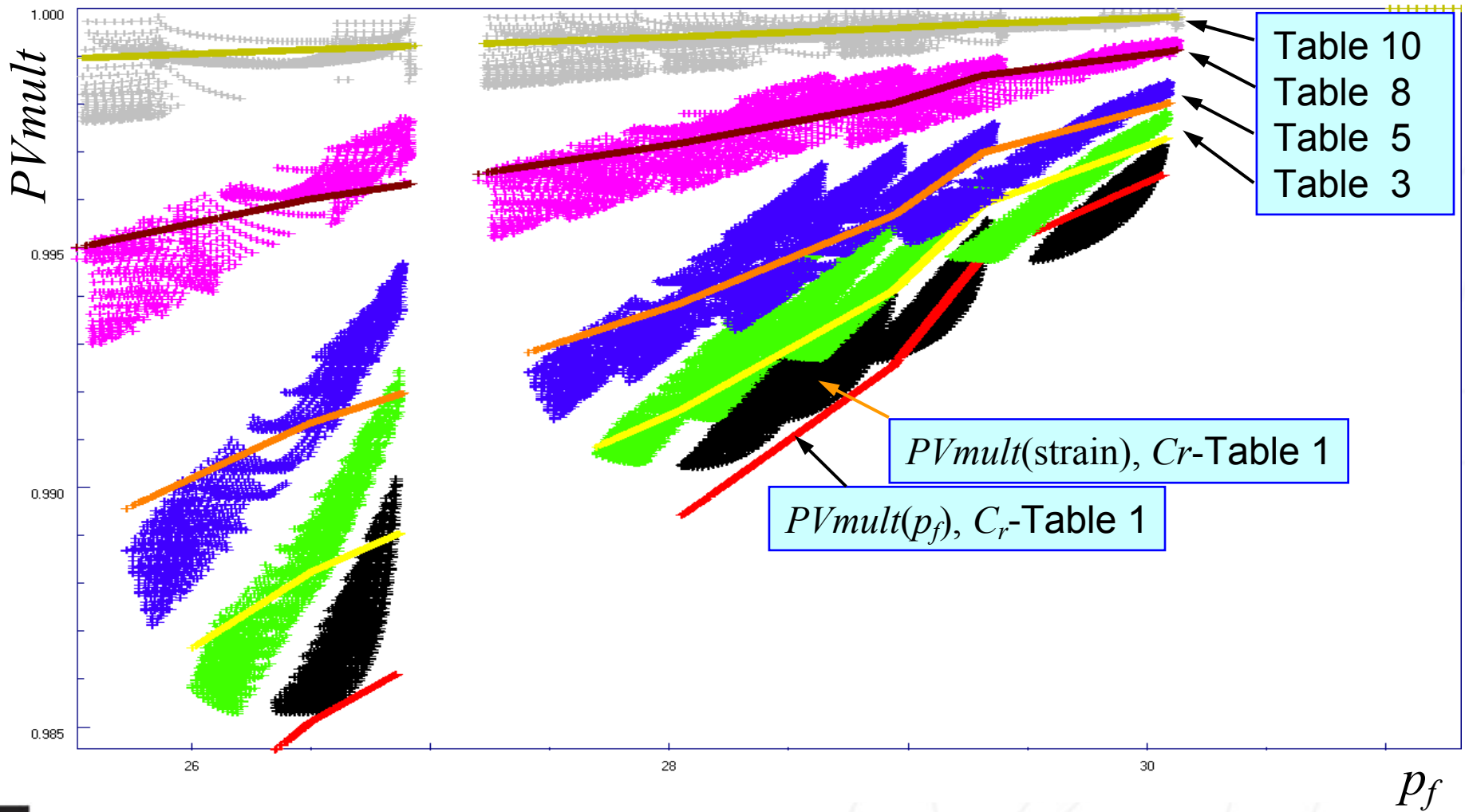


XY layer 7

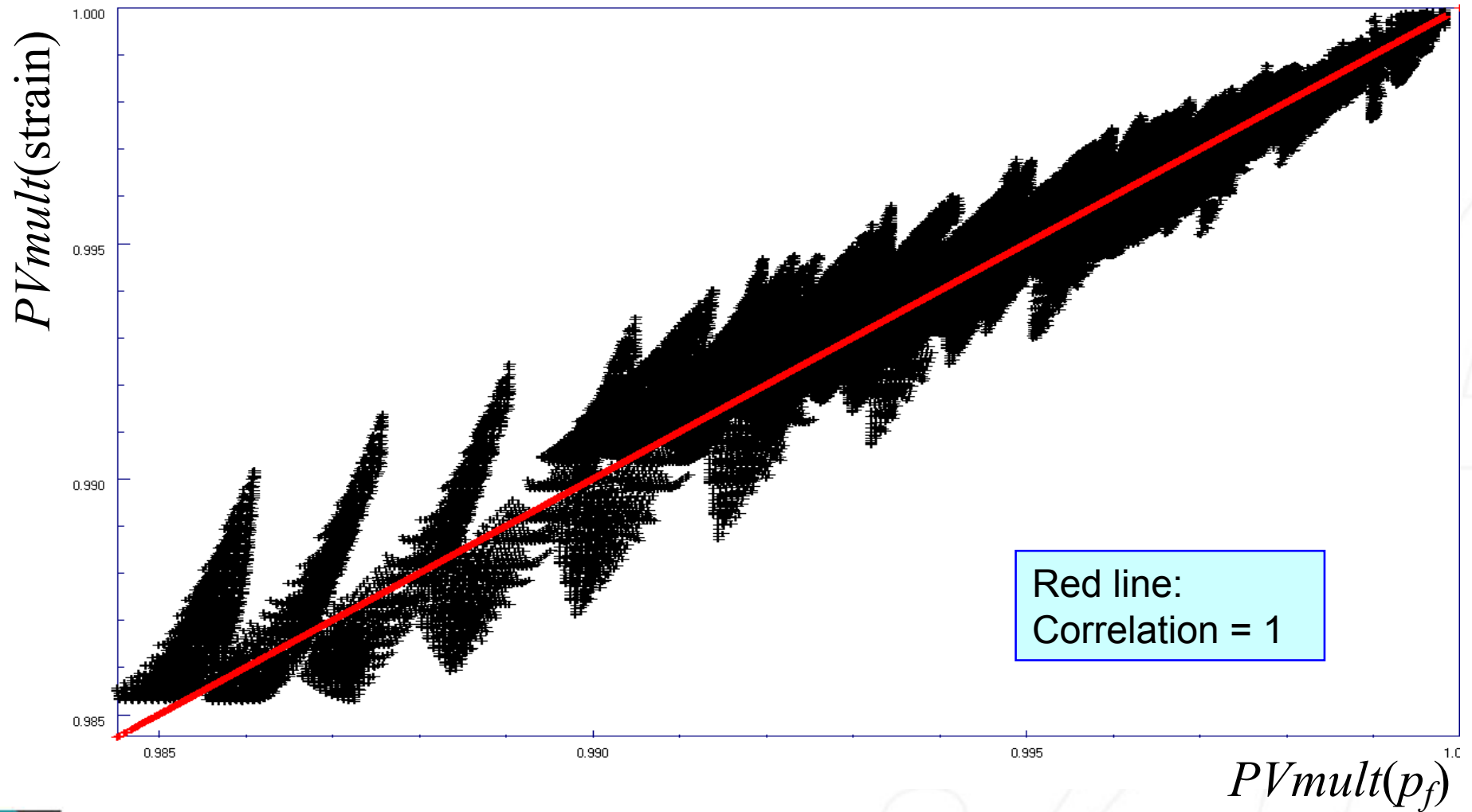
Example Using 10 Material Regions. Compaction Energy Changed \rightarrow Level Invalid



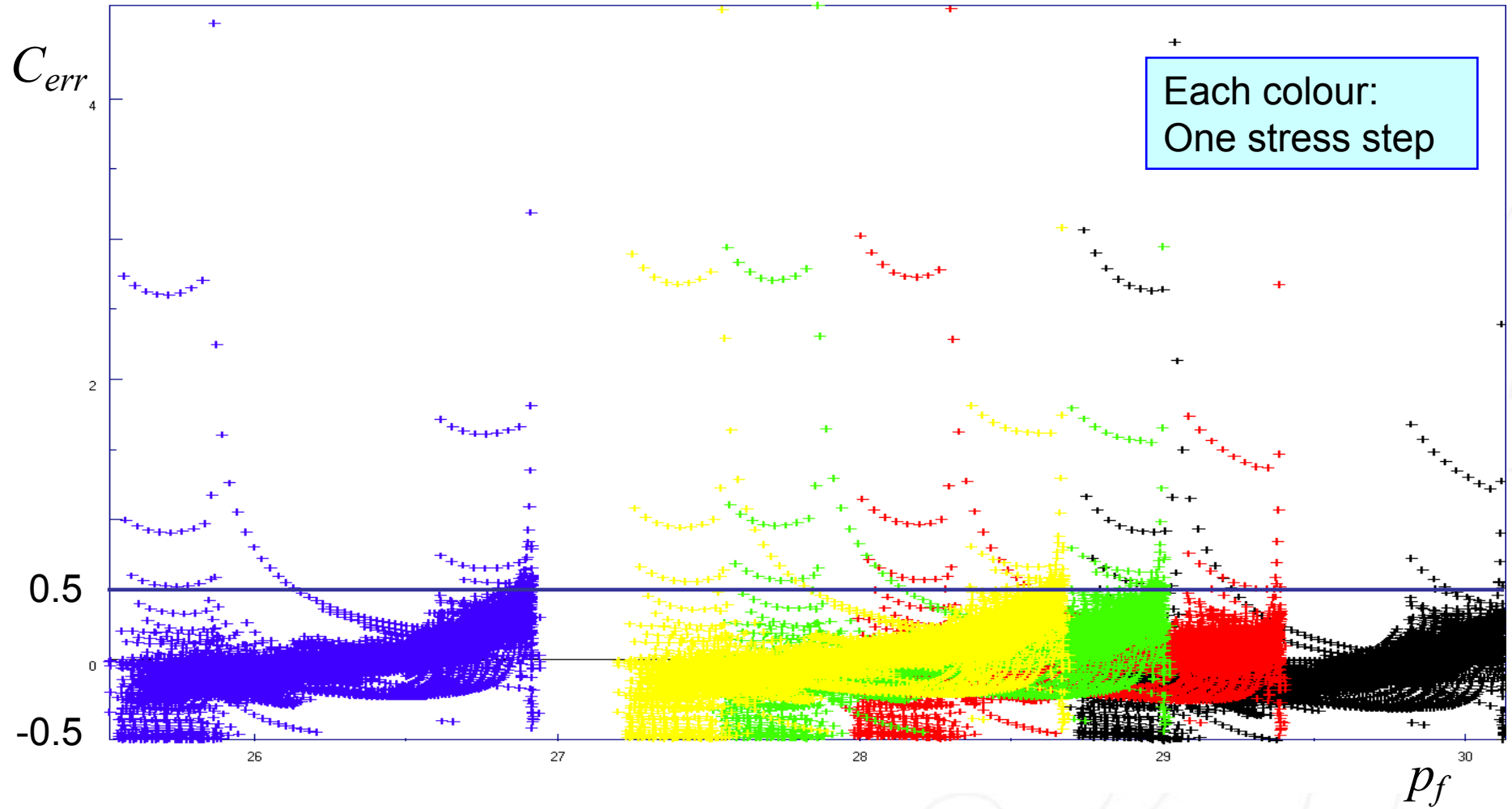
Iteration Step 4: Adjust Level for all 10 Compaction Functions



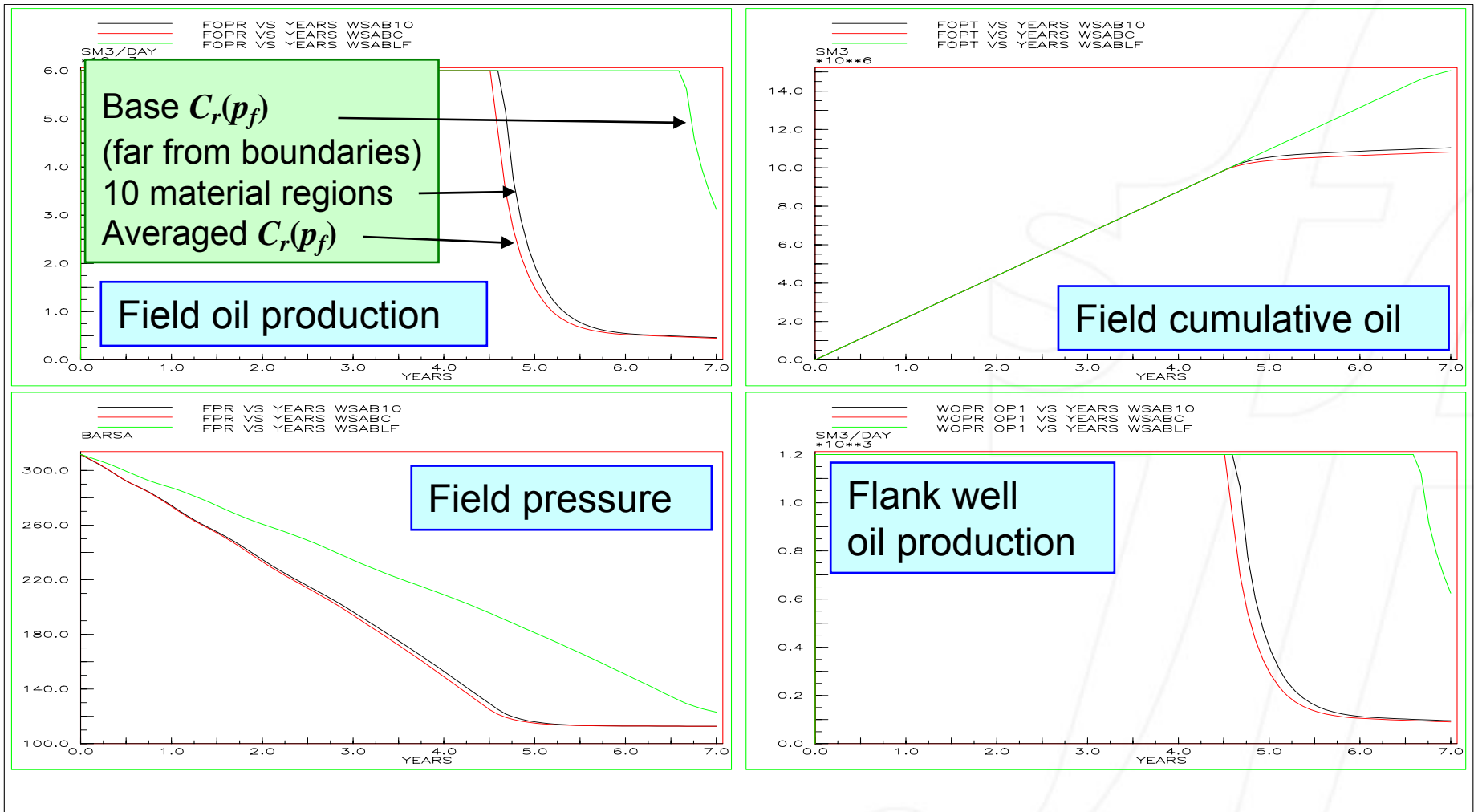
PVmult(strain) vs. PVmult(p_f)



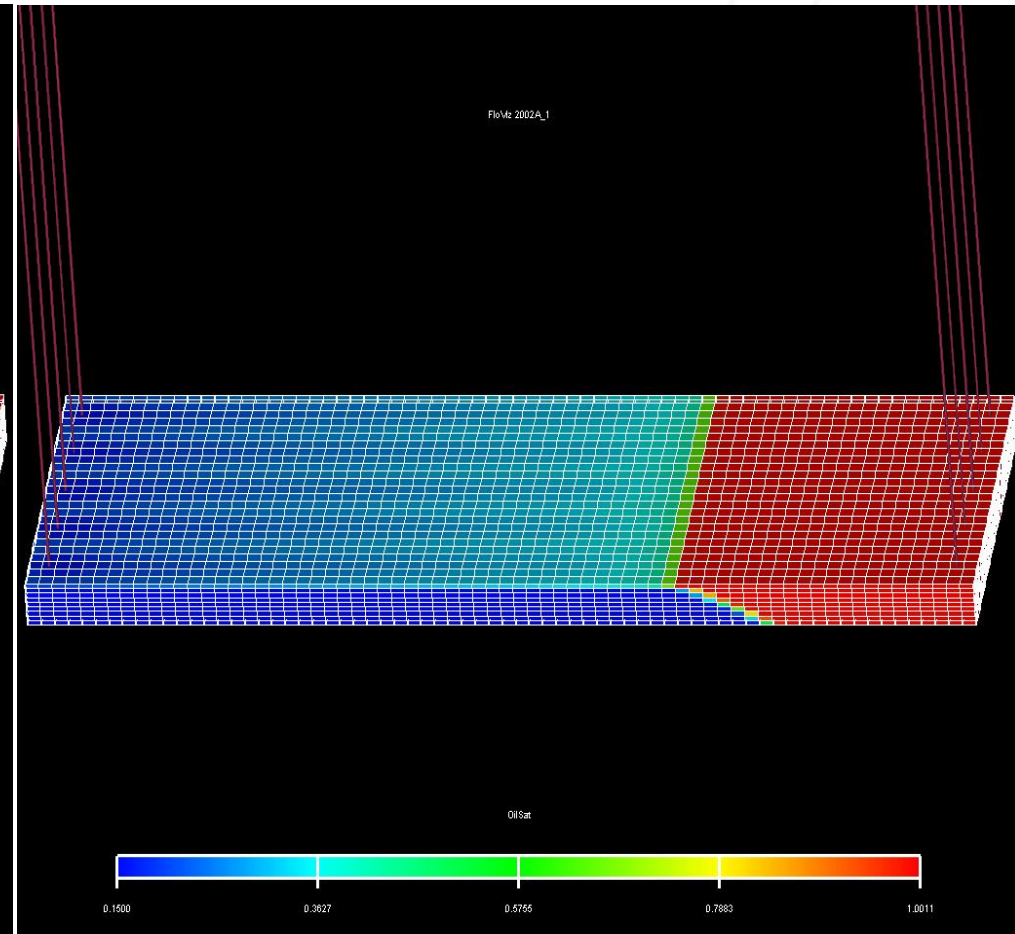
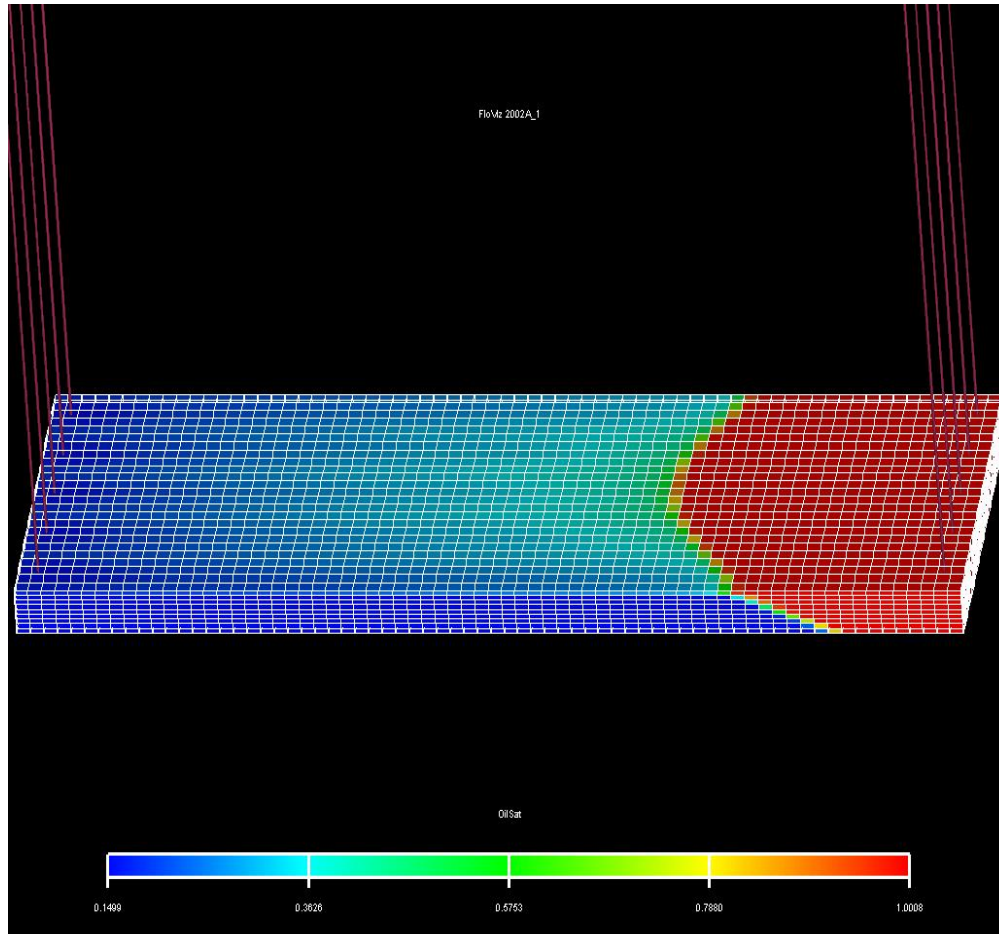
Error in Compaction Computation



Does it Matter? – Simulated Production



Oil Saturation, 10 Material Regions and Averaged $C_r(p_f)$



Comments

- Rock Tables & Material Regions only needs redefining at *some* stress steps
 - ✓ Example run: All updates based on results from stress step no. 2

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- New material regions can be accurately determined in one, or a few iterations
- Total number of Visage runs considerably reduced
- 😊 Improved reservoir simulator compaction functions reduces Visage run time:
 - Example run, CPU time per stress step
 - Iteration step 1: ~15 minutes
 - Iteration step 2: 7-8 minutes
 - Iteration steps 3 & 4: 1-2 minutes

Improved Coupling Scheme:

- Accuracy comparable to fully coupled
- Efficiency comparable to explicit coupled, often better (good predictor)
 - 1-10% of fully coupled run times

Conclusions

- By compaction of sand / sandstone
 - material grows stronger due to tighter packing
 - pore space is permanently deformed
 - Critical State Theory
- Disregarding stress state boundary effects (“arching”) can lead to grave errors, especially for weak materials
- Understanding compaction requires coupled simulations
- An improved coupling scheme has been presented